

Extending the ns-3 Spatial Channel Model for Vehicular Scenarios

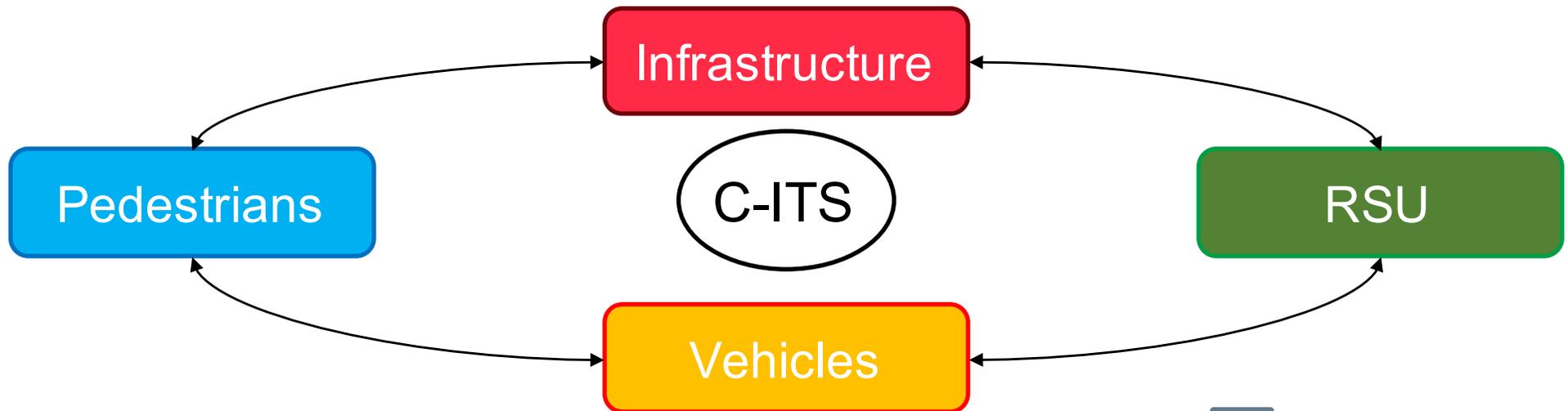
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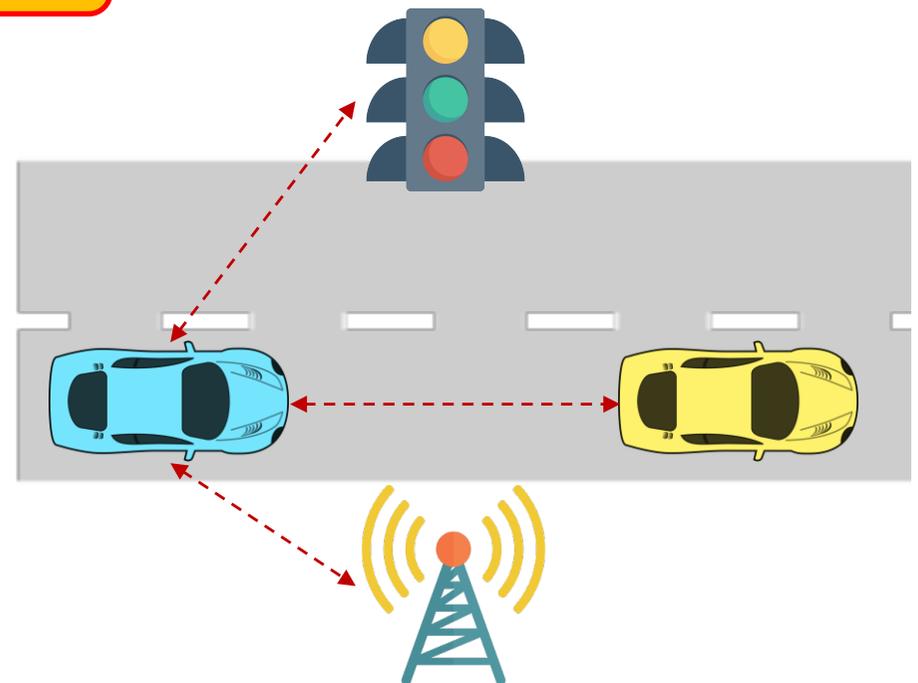
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Introduction

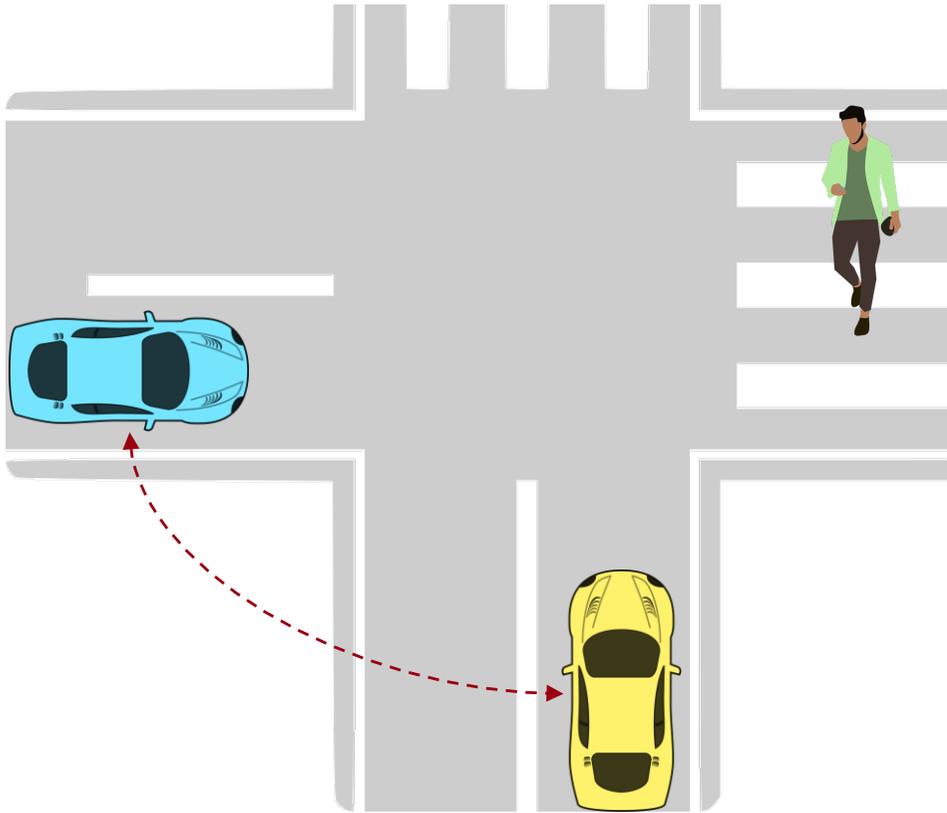


- ✓ Improve traffic safety
- ✓ Enable autonomous driving
- ✓ Reduce carbon emissions
- ✓ Reduce drivers' stress
- ✓ Save many unproductive hours



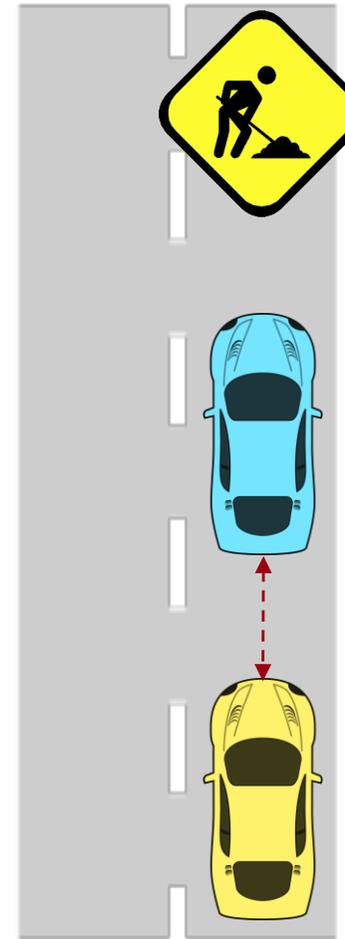
Introduction

Cooperative Perception



Main requirement: high throughput

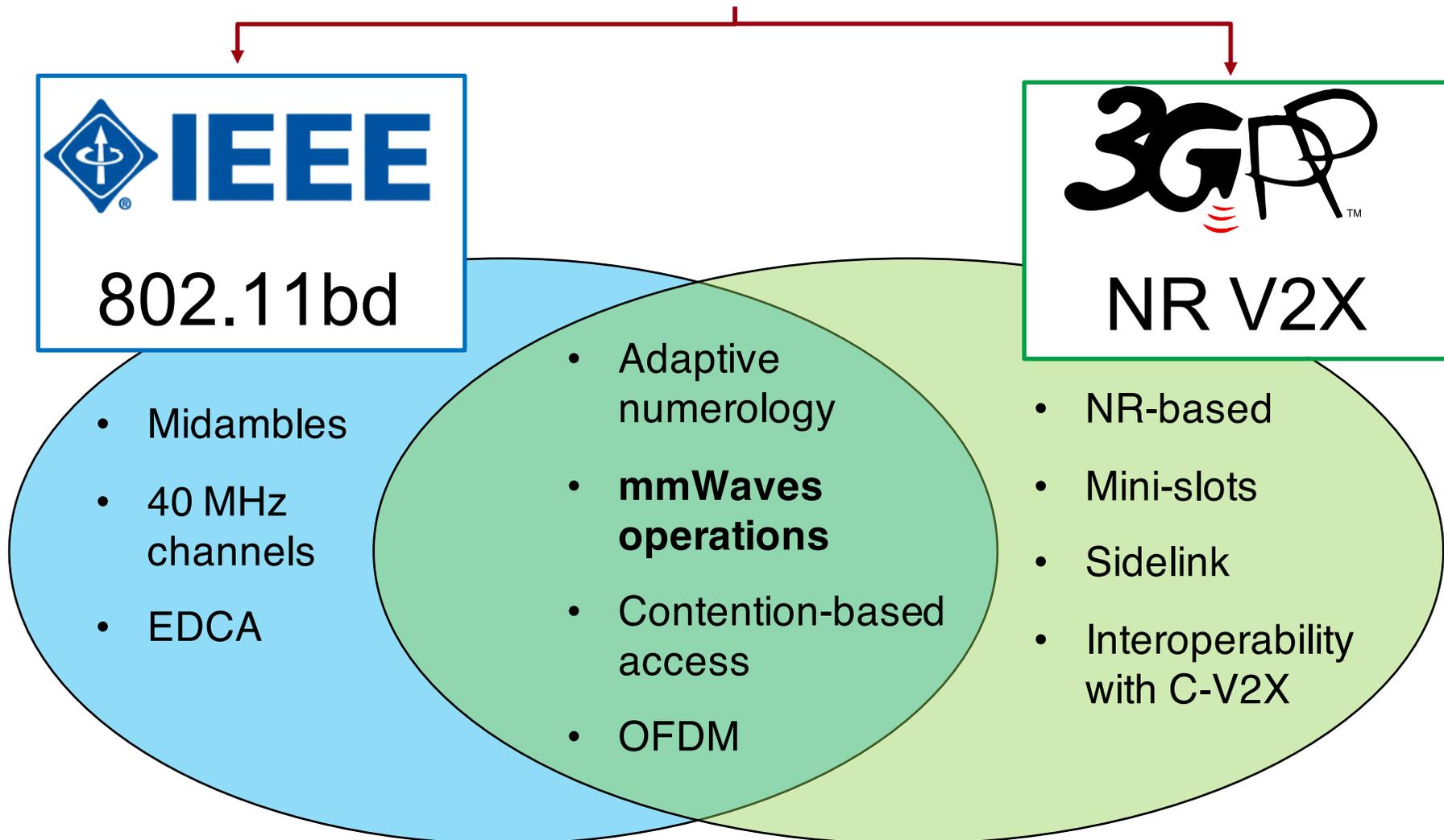
Road Hazard Warning



Main requirement: low latency

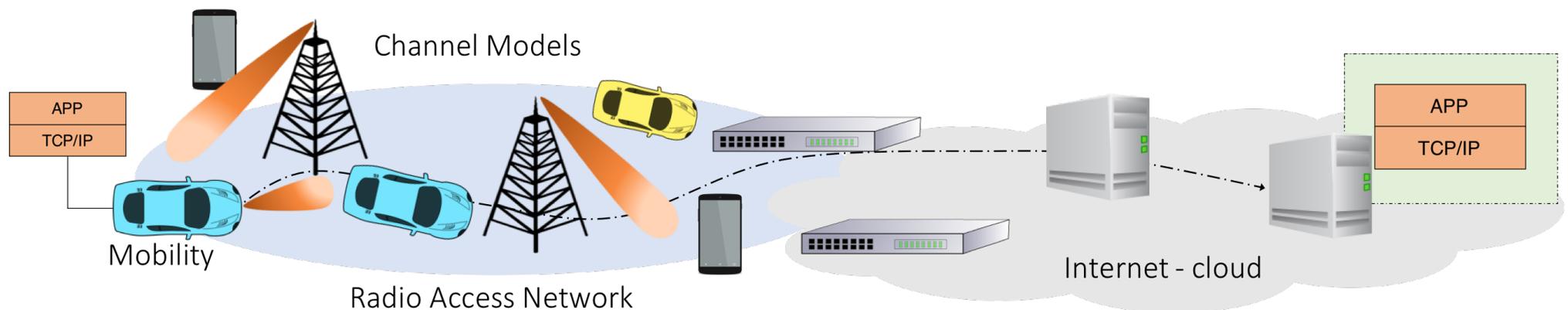
Introduction

New standardization activities

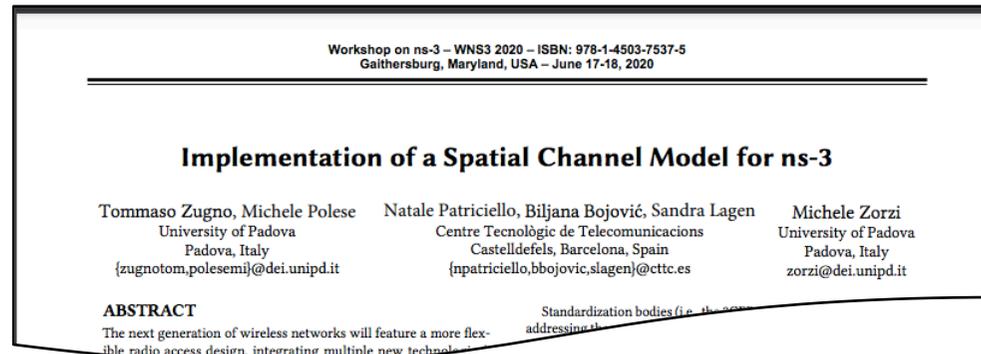


Introduction

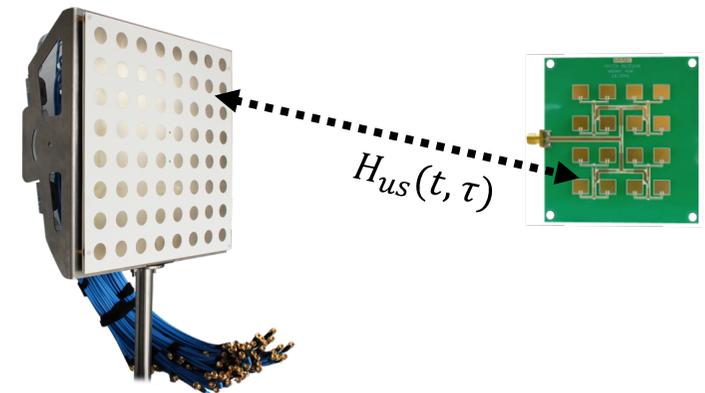
- Simulations are a fundamental tool to evaluate the system performance without the need for a real prototype
- The overall performance depends on how signals propagate through the environment
- The modeling of the communication channel is of primary importance



ns-3 Spatial Channel Model



- ✓ Stochastic Spatial Channel Model (SCM) based on 3GPP TR 38.901
- ✓ Wide frequency range, 0.5 to 100 GHz
- ✓ Different propagation environments
- ✓ Support to multiple antennas



ns-3 Spatial Channel Model

Main limitations:

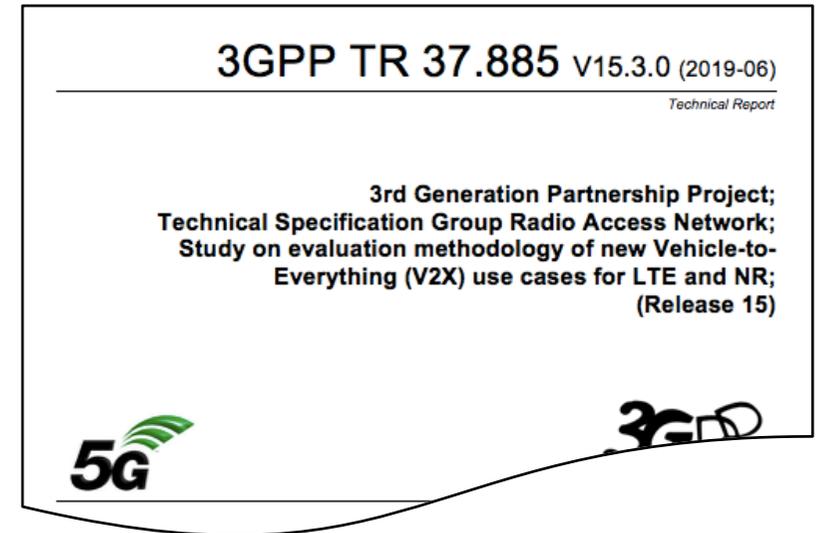
- ✗ supports mobility at a single end of the link
 - ➔ not suitable for the simulation of Vehicle-to-Vehicle (V2V) communications
- ✗ supports “traditional” propagation scenarios
 - ➔ not able to characterize communication between antennas mounted on vehicles



Need for new channel models

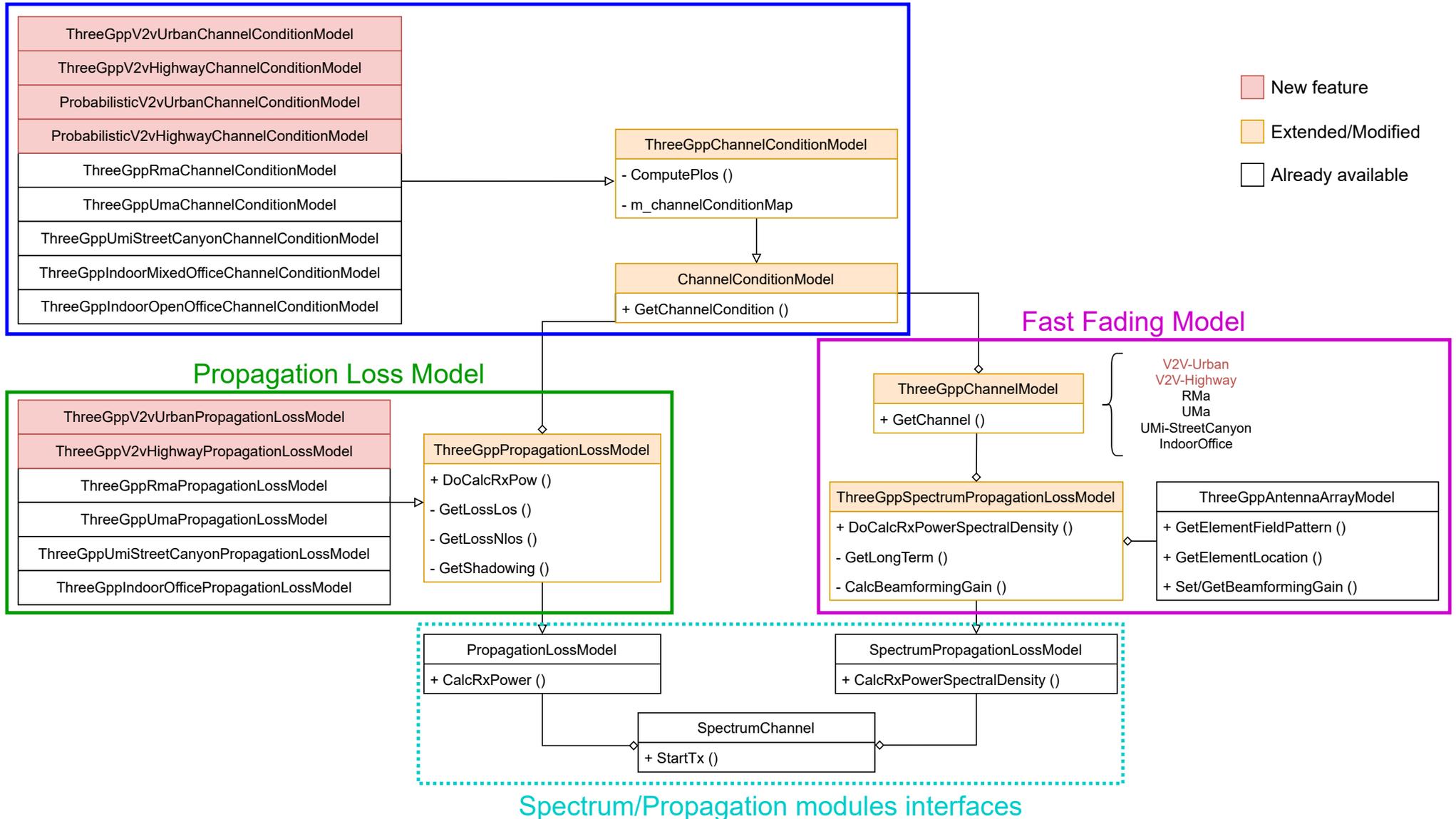
3GPP V2X Channel Model

- Extension of TR 38.901
- New features:
 - mobility of both end terminals
 - modeling of vehicular blockages
 - additional Doppler component
 - new propagation scenarios



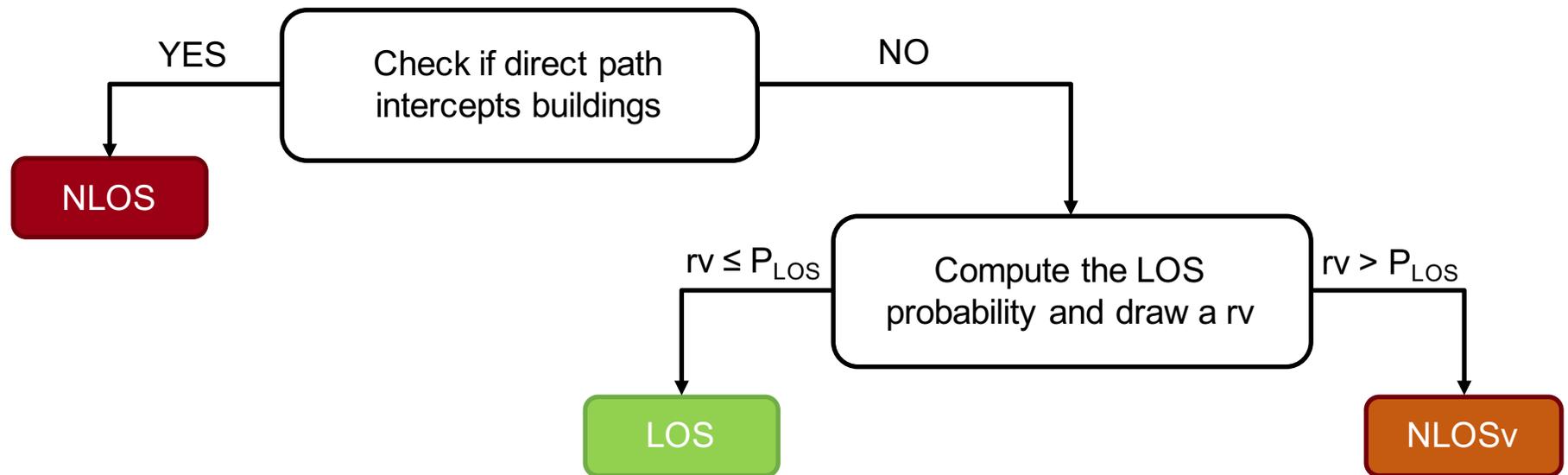
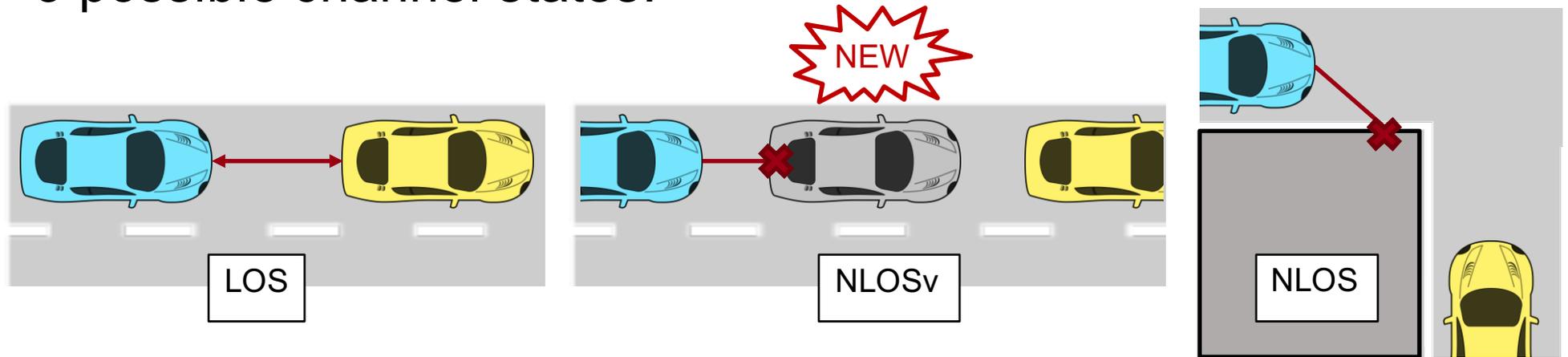
ns-3 implementation

Channel Condition Model



Channel Condition Model

3 possible channel states:

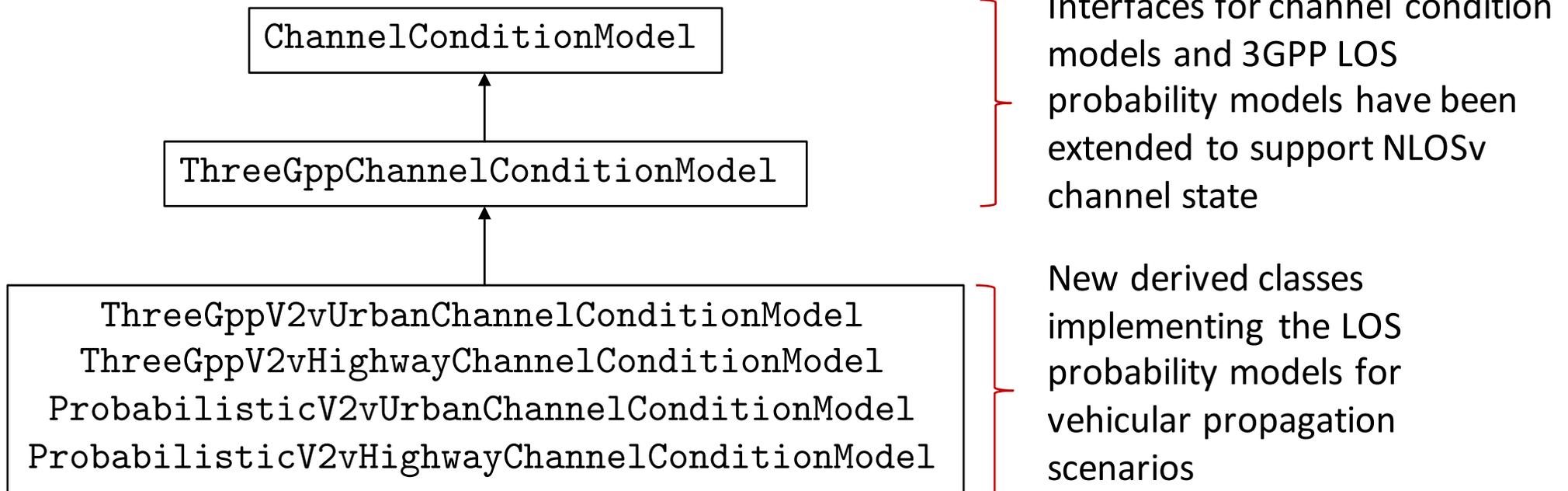


Channel Condition Model

LOS probability models:

	<i>V2V-Urban</i>	<i>V2V-Highway</i>
P_{LOS}	$\min\{1, 1.05 \times \exp(-0.0114 \times d)\}$	$\begin{cases} \min\{1, 2.1013 \times 10^{-6} \times d^2 - 0.002 \times d + 1.0193\} & d \leq 475m \\ \max\{0, 0.54 - 0.001 \times (d - 475)\} & d > 475m \end{cases}$
P_{NLOS_v}	$1 - P_{LOS}$	$1 - P_{LOS}$

ns-3 implementation:



Propagation Loss Model

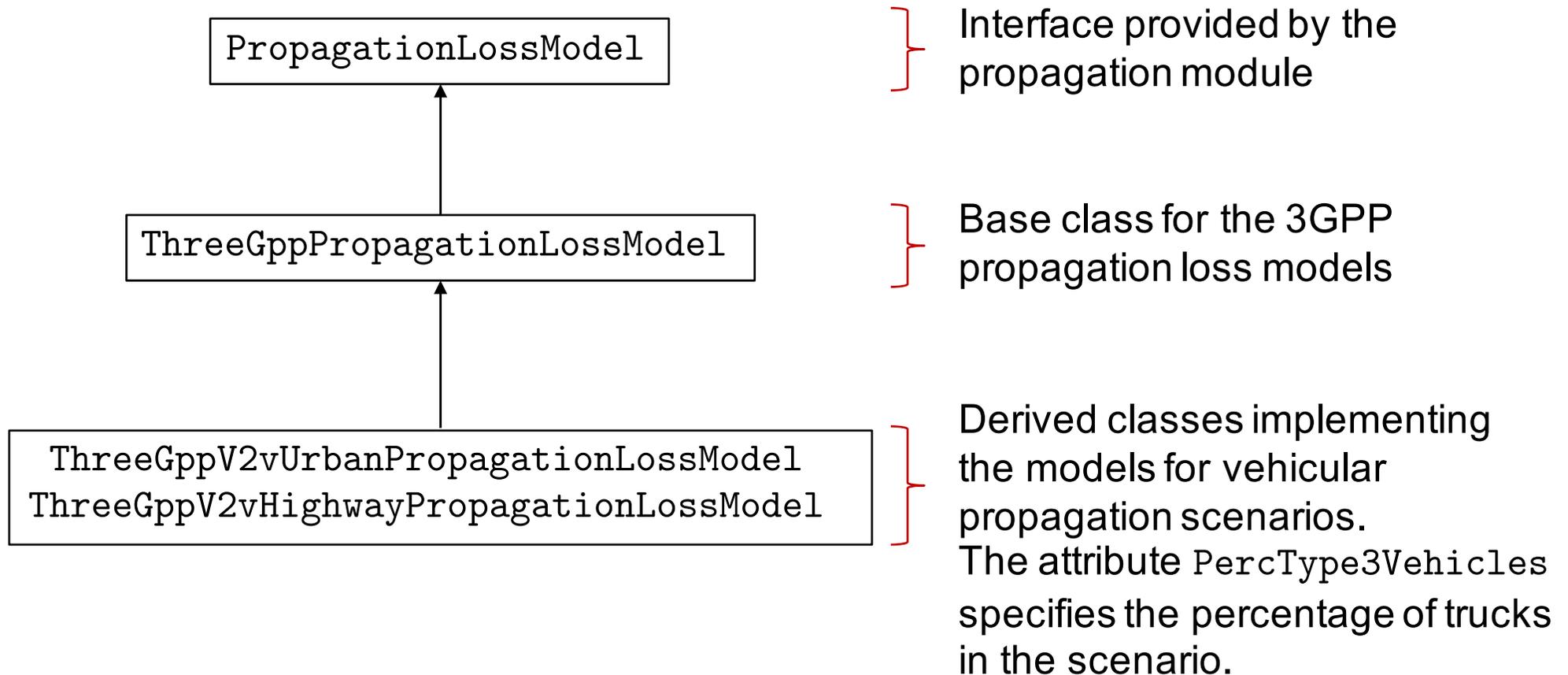
$$PL = A \log_{10}(d) + B + C \log_{10}(f_c) + SF + B_v$$

Propagation Loss Pathloss Shadowing Vehicular blockage

- B_v is a log normal random variable
 - added only in NLOSv conditions
 - distribution depends on the blocker's height
 - 2 vehicle types: cars and trucks
 - blocker's height is randomly determined depending on the percentage of trucks in the scenario

Propagation Loss Model

ns-3 implementation:



Fast Fading Model

- Stochastic model based on 3GPP TR 38.901
- New parameters for vehicular scenarios
- Additional Doppler component to account for scattering in high mobility environments

ns-3 implementation

- Modification of `ThreeGppChannelModel` to include the parameters for V2V-Urban and V2V-Highway scenarios
- Modification of `ThreeGppSpectrumPropagationLossModel` to include the new Doppler component

Example

New example available in ns-3:

`examples/channel-models/three-gpp-v2v-channel`

- shows how the proposed model can be used to extract SNR and propagation loss

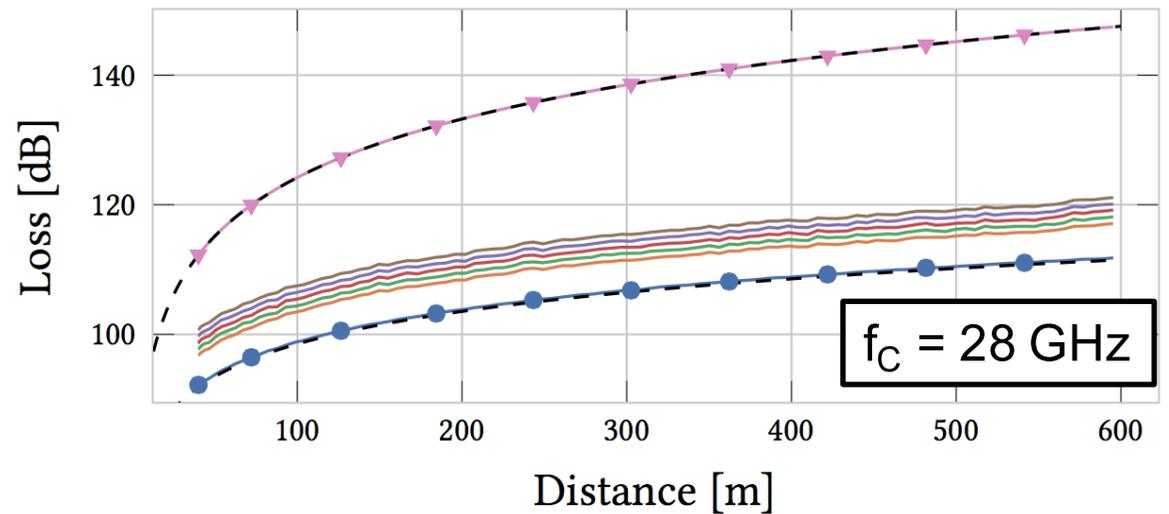
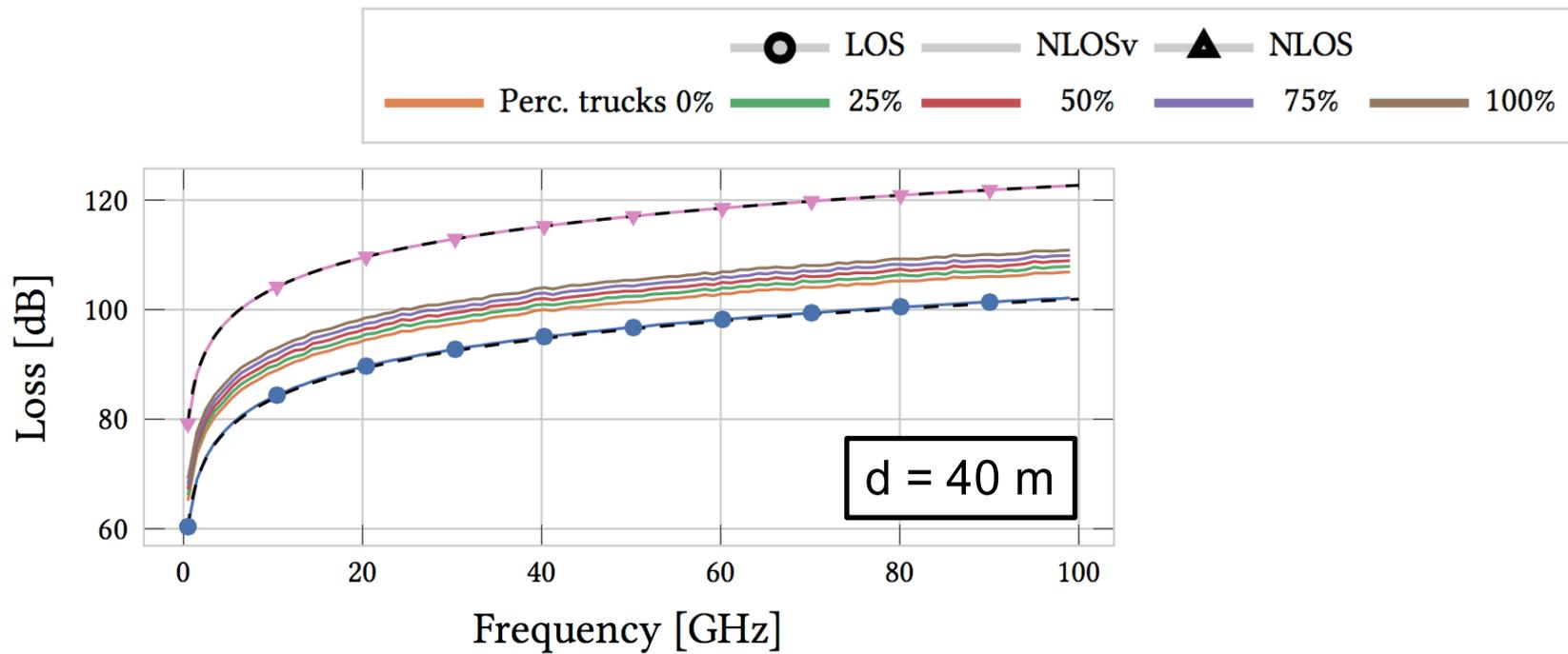
Transmitter parameters

- height: 1.7 m
- tx power: 30 dBm

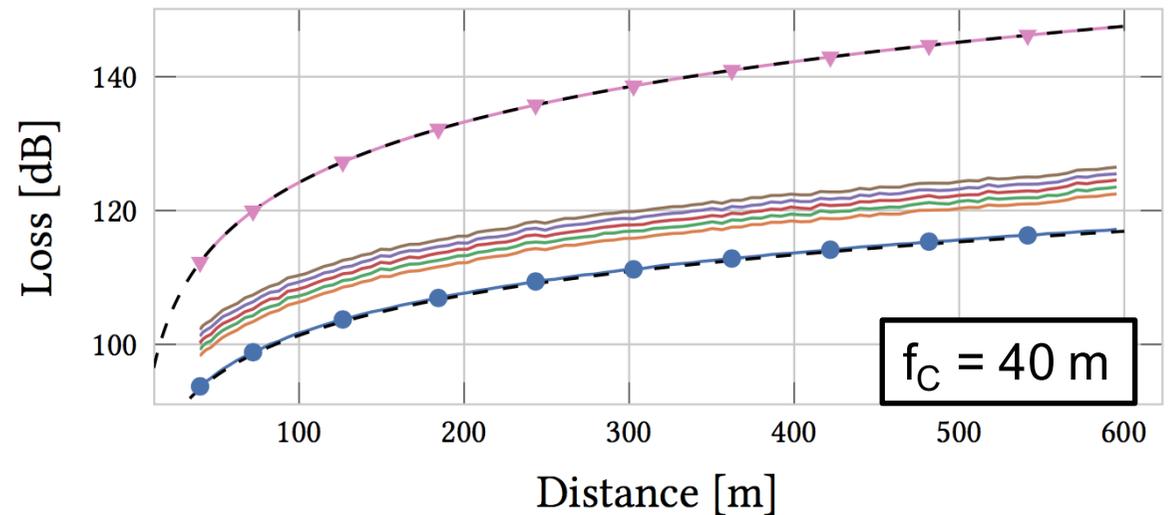
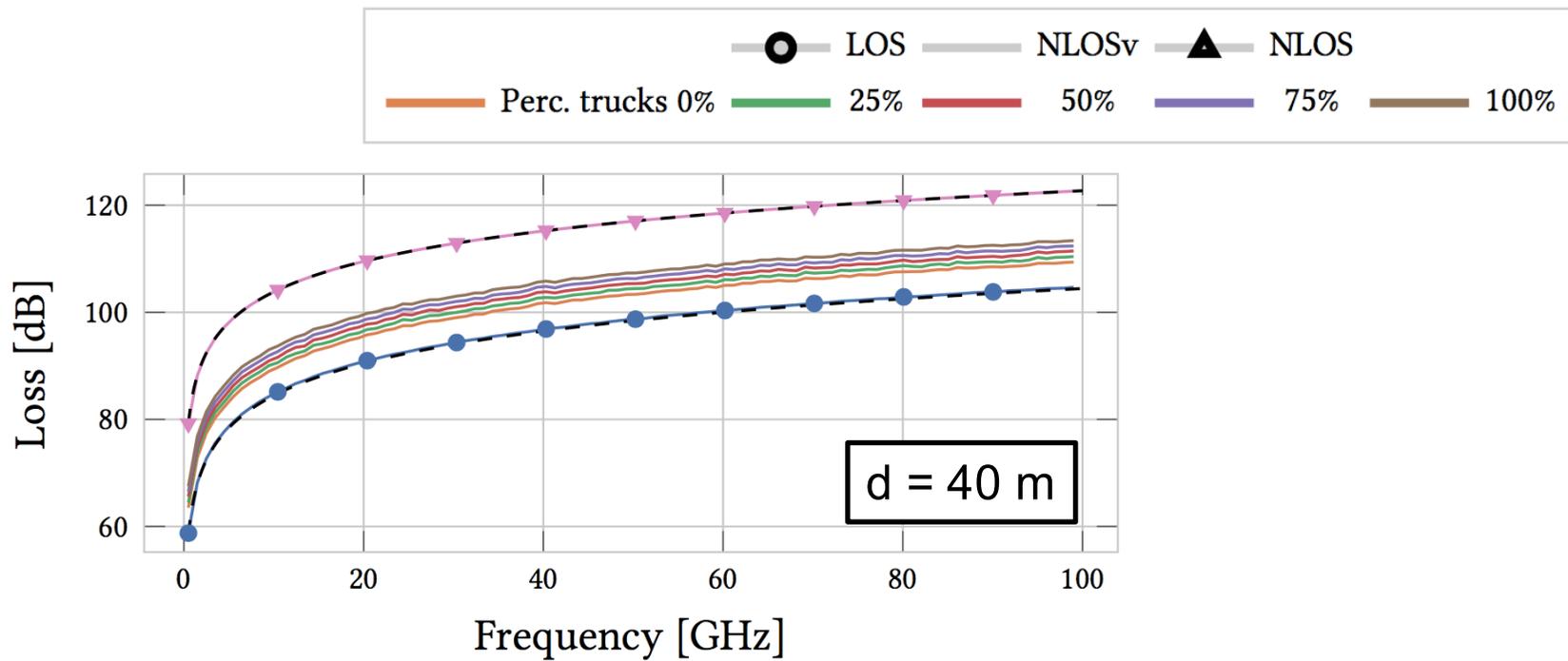
Receiver parameters

- height: 1.5 m
- noise figure: 9 dB

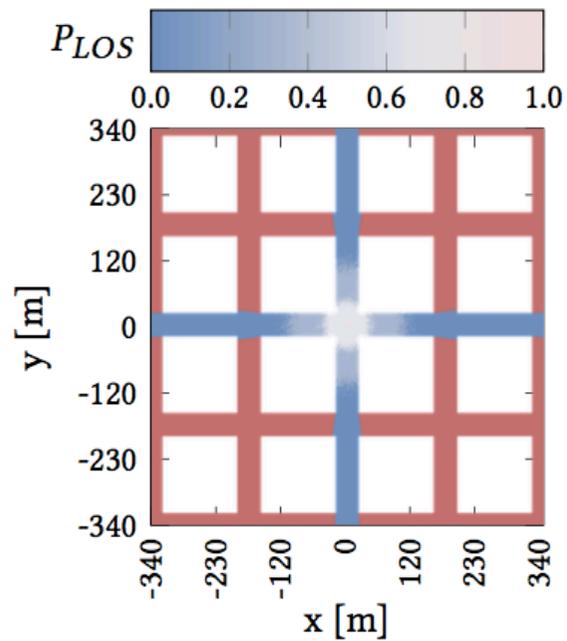
Average Propagation Loss for V2V-Urban



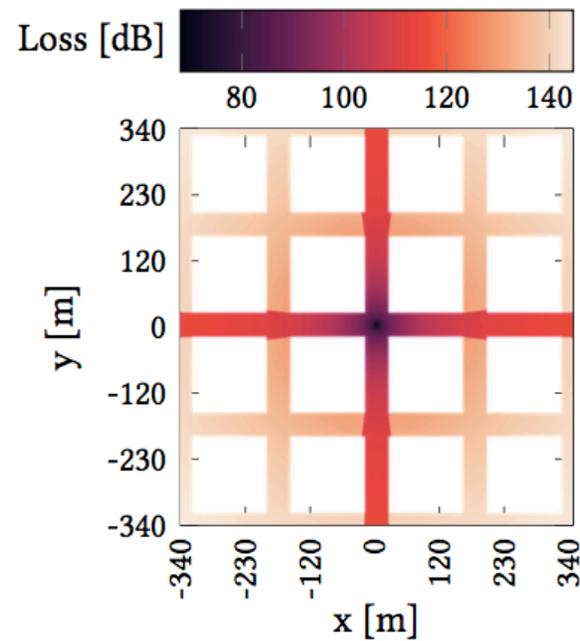
Average Propagation Loss for V2V-Highway



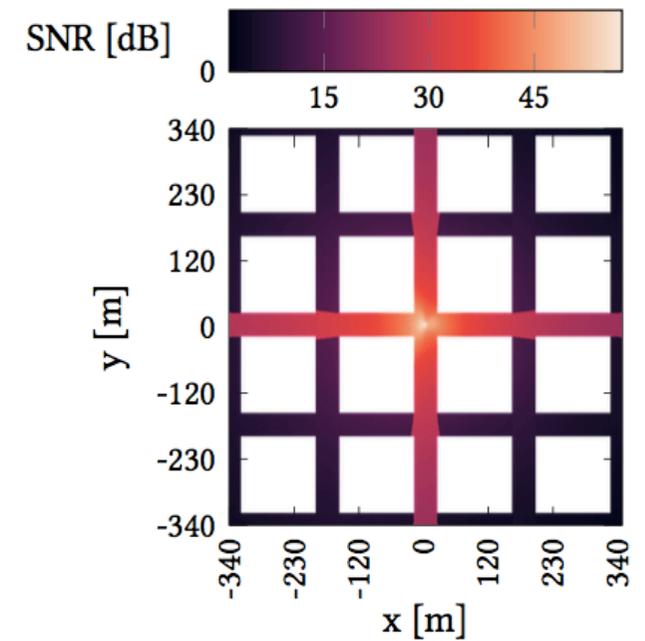
Low-level metrics for V2V-Urban



(a) LOS Probability

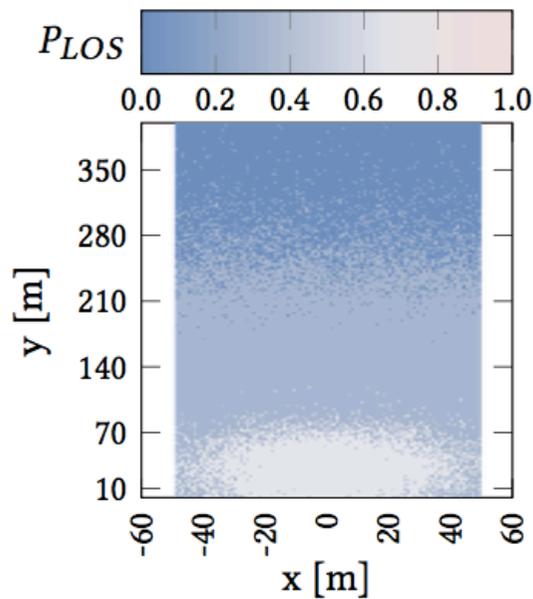


(b) Propagation Loss

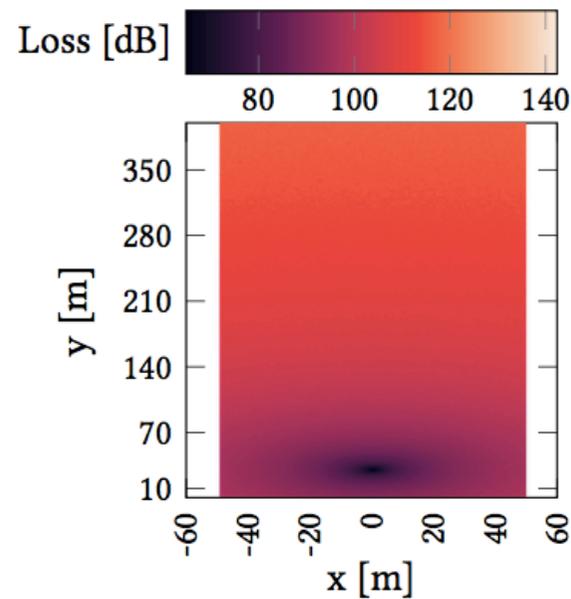


(c) SNR

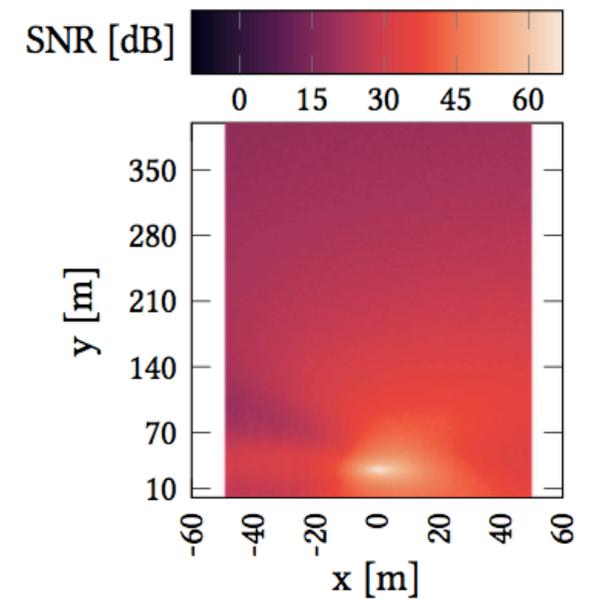
Low-level metrics for V2V-Highway



(a) LOS Probability



(b) Propagation Loss



(c) SNR

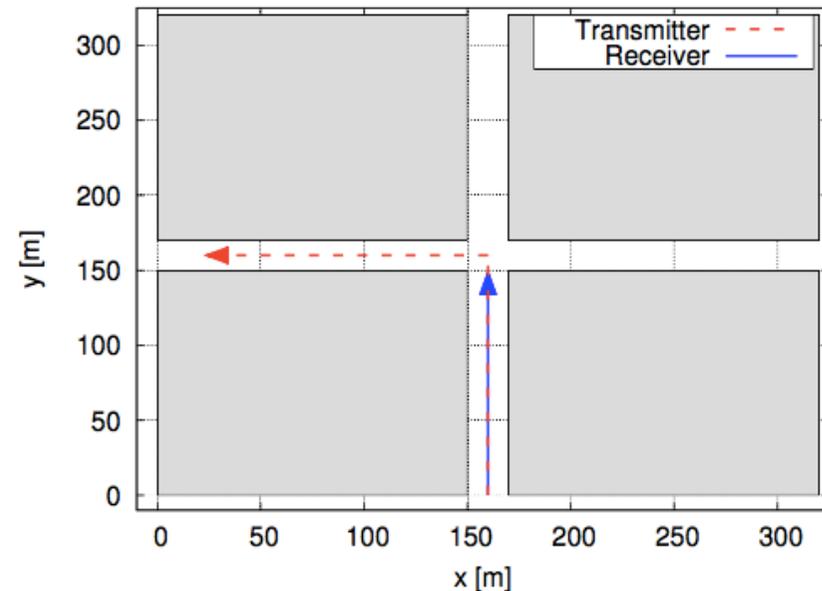
Full Stack Example

Full stack example with MilliCar*

- ns-3 module for the simulation of V2V communications based on the 3GPP NR V2X standard

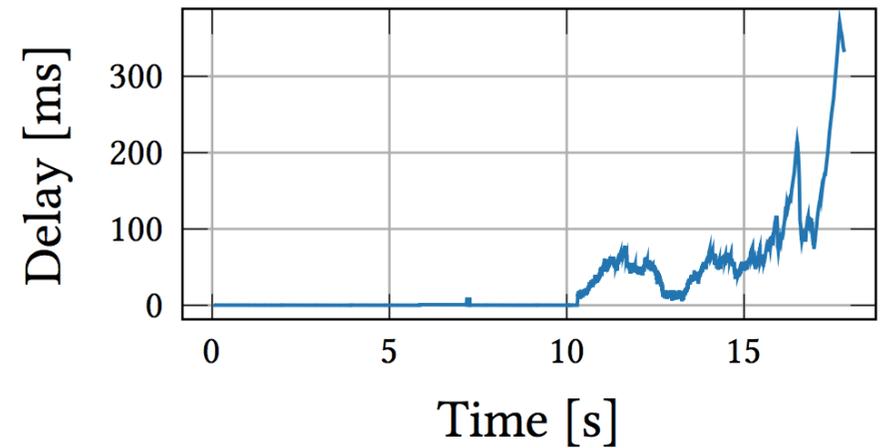
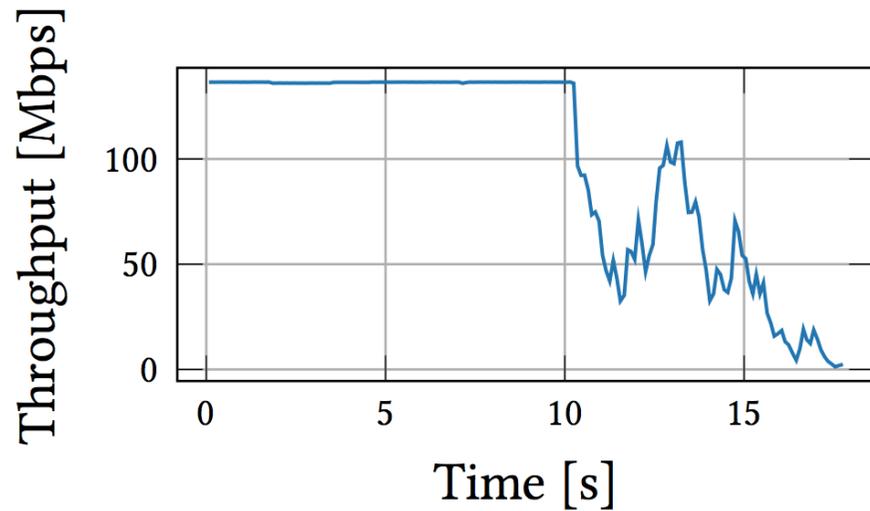
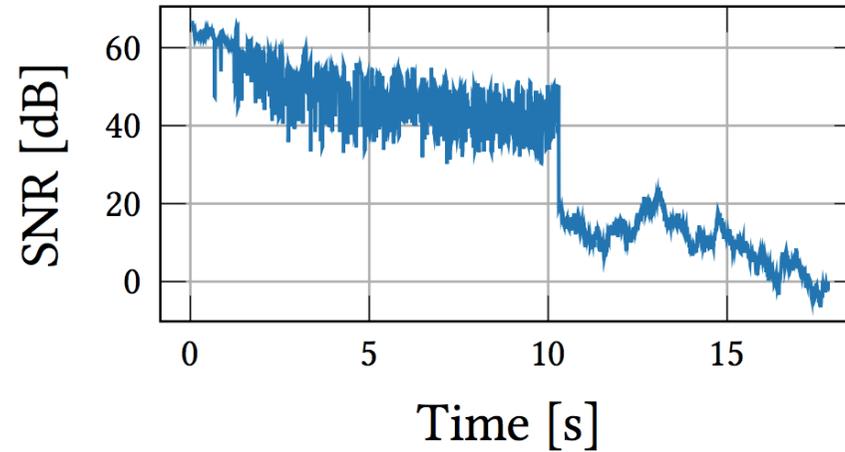
Simulation parameters:

- Data rate: 137 Mbps
- Carrier frequency: 28 GHz
- Bandwidth: 100 MHz
- Channel scenario: V2V-Urban
- Tx speed: 60 km/h
- Rx speed: 30 km/h



* <https://github.com/signetlabdei/millicar>

Full Stack Example



Conclusions

- We presented an extension of the ns-3 SCM for vehicular scenarios
- This model enables full-stack simulations of vehicular communication technologies
- We provide low-level and system-level examples to illustrate the usage and effectivity of this model
- Already available in ns-3 (starting from release 33)

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